

# **Vector VS330 GNSS Compass**

### **Professional Heading and Positioning Receiver**





#### **Vector** VS330

Experience the Vector™VS330™ with Eclipse™ GNSS technology, an addition to our Vector VS family. Developed for precise marine and land applications which require precise heading and RTK position performance from the Vector VS330 GNSS receiver compass.

The Vector VS330 utilizes all of the innovations in Hemisphere GPS' Eclipse Vector technology. Optimizing Eclipse Vector technology brings a series of new features to the Vector VS330 including heave, pitch and roll output, and more robust heading and positioning performance.

The Vector VS330 receiver, with its display and user interface, can be conveniently installed near the operator. The two antennas are mounted separately and with a user-determined separation to meet the desired heading accuracy.

The Vector VS330 uses L-band DGNSS/HP/XP and SBAS (WAAS, EGNOS, MSAS, etc.) for differential GPS positioning.

### **Key Vector VS330 GNSS Receiver Advantages**

- Extremely accurate heading with both short and long
  Fast RTK acquision and reacquisition times baselines up to 10 km
- L1/L2 GPS/GLONASS RTK capable
- L-band DGNSS/HP/XP(OmniSTAR®) capable
- Beacon capable

- Excellent coasting performance
- 5 cm rms RTK-enabled heave accuracy
- Strong multipath mitigation and interference rejection



## **Vector VS330 GNSS Compass**

**GPS Sensor Specifications** 

Vector GNSS L1/L2 RTK ReceiverType: Signals Received: GPS, GLONASS, Galileo8

Channels: 270 GPS Sensitivity: -142dBm

SBAS Tracking: 3-channel, parallel tracking

Update Rate: 10 Hz standard, 20 Hz available by subscription Horizontal Accuracy: RMS (67%) 2DRMS (95%)

RTK: 1 L-band DGNSS/HP/XP

(OmniSTAR HP): 2,7 0.08 m  $0.16 \, \text{m}$ SBAS (WAAS): 2 0.25 m 0.50 m Autonomous, no SA: 2 1.2 m 2.5 m

Heading Accuracy: < 0.17° rms @ 0.5 m antenna separation

10 mm + 1 ppm

< 0.09° rms @ 1.0 m antenna separation < 0.04° rms @ 2.0 m antenna separation < 0.02° rms @ 5.0 m antenna separation < 0.01° rms @ 10.0 m antenna seperation

20 mm + 2 ppm

Pitch/Roll Accuracy: < 1° rms

30 cm (DGPS)5,10 cm (RTK)6 Heave Accuracy:

Timing (1PPS) Accuracy: 20 ns

Rate of Turn: 100°/s maximum

Compass Safe

Distance: 30 cm (with enclosure)5 Cold Start: < 40 s (no almanac or RTC) Warm Start: < 20 s typical (almanac and RTC)

Hot Start: < 5 s typical (almanac, RTC and position) Heading Fix: < 10 s typical (valid position)

1,850 mph (999 kts) Maximum Speed: Maximum Altitude: 18,288 m (60,000 ft)

**Beacon Sensor Specifications** 

2-channel, parallel tracking Channels:

Frequency Range: 283.5 to 325 kHz

Manual, automatic and database Operating Modes: Compliance: IEC 61108-4 beacon standard

L-band DGNSS/HP/XP Sensor Specifications

Sensitivity: -130 dBm Channel Spacing: 7.5 KHz

Satellite Selection: Manual and Automatic 15 seconds (typical) ReacquisitionTime: 15 kHz spacing > 30 dB, 300 kHz spacing > 60 dB Rejection:

DSP for demodulation and protocol decoding Processor: module provides processing for the differential

algorithms

Reports L-band DGNSS/HP/XP(OmniSTAR) region, Command Support:

satellite info, allows input and status of L-band DGNSS/HP/XP (OmniSTAR) subscription, Bit Error Rate (BER) output for reception quality indication

and manual frequency tuning

Communications

Serial Ports: 4 full-duplex RS232, 1 full-duplex RS422 ports

**USB Ports:** 

**Baud Rates:** Correction I/O Protocol: RTCM v2.3 (DGPS), RTCM v3 (RTK), CMR, CMR+1 Data I/O Protocol: NMEA 0183, Crescent binary

Timing Output:

**Power** 

Input Voltage: **Power Consumption:** 

**Current Consumption:** 

Power Isolation:

8 to 36 VDC < 6.2 W nominal (GPS (L1/L2), GLONASS (L1/L2) and L-band DGNSS/HP/XP) < 5.3 W nominal (GPS L1/L2) and GLONASS

(L1/L2))

10 kΩ, 10pF load

< 0.52 A nominal (GPS L1/L2), GLONASS (L1/L2) and L-band DGNSS/HP/XP) < 0.44 A nominal (GPS L1/L2) and GLONASS

1PPS CMOS, active low, falling edge sync,

(L1/L2)) 500 V

**Reverse Polarity Protection:** Antenna Short Circuit Protection: Yes 50 Ω

Antenna Input Impedance:

**Environmental** 

Operating Temperature: Storage Temperature: Humidity: -30°C to + 70°C (-22°F to + 158°F) -40°C to + 85°C (-40°F to + 185°F) 95% non-condensing (when installed in an

**Enclosure Rating:** 

Shock and Vibration:

Mechanical Shock: EP455 Section 5.14.1 Operational (when mounted in an enclosure with screw mounting holes utilized) EP455

IP66 (IEC 60529)

enclosure)

Vibration: Section 5.15.1 Random CE (IEC 60945 Emissions and Immunity)

FCC Part 15, Subpart B

CISPR22

Mechanical

EMC:

20.2 L x 12.0 W x 7.5 H (cm) Dimensions: 8.0 L x 4.7 W x3.0 H (in)

Weight: ~1.1 kg (~2.5 lbs.)

Status Indications (LED): Power, Primary and Secondary GPS lock, Differential lock, DGPS position, Heading, RTK lock, L-band DGNSS/HP/XP lock

Power Switch: Front panel soft switch Power/Data Connector: 9-pin ODU metal circular Power Connector: 2-pin ODU metal circular Data Connector:

DB9 (sealed) Antenna Connectors: 2TNC (female)

**Aiding Devices** 

Tilt Sensors:

Gyro:

Provides smooth heading, fast heading reacquisition and reliable < 5° per minute heading for periods up to 3 minute when loss of GPS has occurred 4

Provide pitch, roll data and assist in fast start-up and reacquisition of heading solution.

Authorized Distributor:

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Depends on multipath environment, number of satellites in view, satellite geometry, baseline length (for local services), and ionospheric activity

<sup>2</sup> Depends on multipath environment, number of satellites in view and satellite geometry

<sup>3</sup> Hemisphere GPS proprietary

<sup>4</sup> Under static conditions

5 This is the minimum safe distance measured when the product is placed in the vicinity of the steering magnetic compass. The ISO 694 defines "vicinity" relative to the compass as within 5 m (16.4 ft) separation.

<sup>6</sup> Based on a 40 second time constant

Requires a subscription from OmniSTAR

<sup>8</sup> Upgrade required





